HEF4021B

8-bit static shift register

Rev. 10 — 21 March 2016

Product data sheet

1. General description

The HEF4021B is an 8-bit static shift register (parallel-to-serial converter) with a synchronous serial data input (DS), a clock input (CP), an asynchronous active HIGH parallel load input (PL), eight asynchronous parallel data inputs (D0 to D7) and buffered parallel outputs from the last three stages (Q5 to Q7).

Each register stage is a D-type master-slave flip-flop with a set direct (SD) and clear direct (CD) input. Information on D0 to D7 is asynchronously loaded into the register while PL is HIGH, independent of CP and DS. When PL is LOW, data on DS is shifted into the first register position and all the data in the register is shifted one position to the right on the LOW-to-HIGH transition of CP. Schmitt trigger action makes the clock input highly tolerant of slower rise and fall times.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD} , V_{SS} , or another input.

2. Features and benefits

- Tolerant of slower rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from –40 °C to +125 °C
- Complies with JEDEC standard JESD 13-B

3. Ordering information

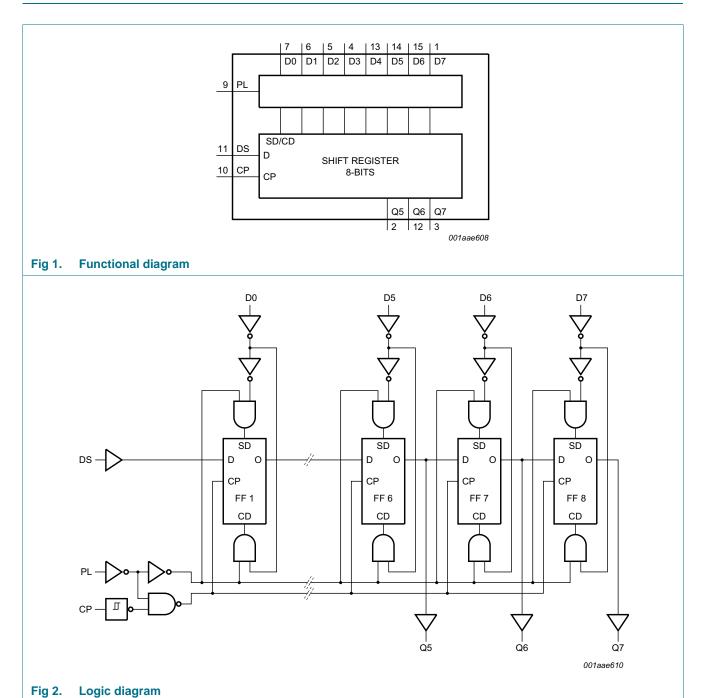
Table 1. Ordering information

All types operate from -40 °C to +125 °C.

Type number	Package	ackage						
	Name	ame Description Ver						
HEF4021BT	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1					
HEF4021BTT	TSSOP16	plastic thin shrink small outline package; 16 leads; body width 4.4 mm	SOT403-1					

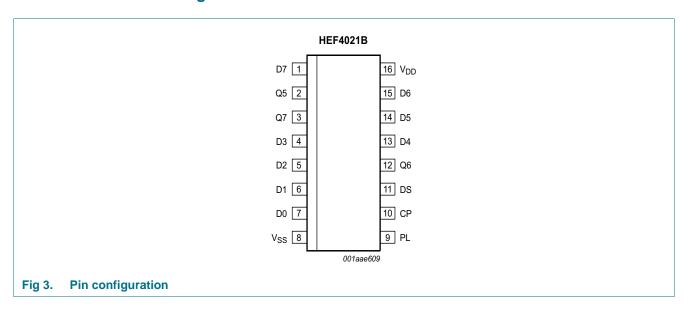


4. Functional diagram



5. Pinning information

5.1 Pinning



5.2 Pin description

Table 2. Pin description

Symbol	Pin	Description
Q5 to Q7	2, 12, 3	buffered parallel output from the last three stages
D0 to D7	7, 6, 5, 4, 13, 14,15, 1	parallel data input
V _{SS}	8	ground supply voltage
PL	9	parallel load input
СР	10	clock input (LOW-to-HIGH edge-triggered)
DS	11	serial data input
V_{DD}	16	supply voltage

6. Functional description

Table 3. Function table[1]

Number of clock	Inputs			Outputs	Outputs			
transitions	CP DS		PL	Q5	Q6	Q7		
Serial operation		'	1	'	,	'		
1	↑	data 1	L	X	X	X		
2	\uparrow	data 2	L	X	X	Х		
3	\uparrow	data 3	L	Х	Х	Х		
6	\uparrow	Х	L	data 1	Х	Х		
7	\uparrow	Х	L	data 2	data 1	Х		
8	\uparrow	Х	L	data 3	data 2	data 1		
	\downarrow	Х	L	no change	no change	no change		
Parallel operation	1			•				
	X	X	Н	D5	D6	D7		

^[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; \uparrow = LOW to HIGH clock transition; \downarrow = HIGH to LOW clock transition; data n = data (HIGH or LOW) on the DS input at the nth \uparrow CP transition.

7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V_{DD}	supply voltage		-0.5	+18	V
I _{IK}	input clamping current	$V_I < -0.5 \text{ V or } V_I > V_{DD} + 0.5 \text{ V}$	-	±10	mA
VI	input voltage		-0.5	V _{DD} + 0.5	V
I _{OK}	output clamping current	$V_{O} < -0.5 \text{ V or } V_{O} > V_{DD} + 0.5 \text{ V}$	-	±10	mA
I _{I/O}	input/output current		-	±10	mA
I _{DD}	supply current		-	50	mA
T _{stg}	storage temperature		-65	+150	°C
T _{amb}	ambient temperature		-40	+125	°C
P _{tot}	total power dissipation	T _{amb} –40 °C to +125 °C			
		SO16 and TSSOP16 package	-	500	mW
Р	power dissipation	per output	-	100	mW

^[1] For SO16 package: P_{tot} derates linearly with 8 mW/K above 70 °C. For TSSOP16 package: P_{tot} derates linearly with 5.5 mW/K above 60 °C.

8. Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V_{DD}	supply voltage		3	-	15	V
VI	input voltage		0	-	V_{DD}	V
T _{amb}	ambient temperature	in free air	-40	-	+125	°C
Δt/ΔV	input transition rise and fall rate	V _{DD} = 5 V	-	-	3.75	μs/V
		V _{DD} = 10 V	-	-	0.5	μs/V
		V _{DD} = 15 V	-	-	0.08	μs/V

9. Static characteristics

Table 6. Static characteristics

 $V_{SS} = 0$ V; $V_I = V_{SS}$ or V_{DD} unless otherwise specified.

Symbol	Parameter	Conditions	V_{DD}	T _{amb} =	–40 °C	T _{amb} =	25 °C	T _{amb} =	85 °C	T _{amb} =	125 °C	Unit
				Min	Max	Min	Max	Min	Max	Min	Max	
V _{IH}	HIGH-level	$ I_{O} < 1 \mu A$	5 V	3.5	-	3.5	-	3.5	-	3.5	-	V
	input voltage		10 V	7.0	-	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	11.0	-	V
V _{IL}	LOW-level	$ I_{O} < 1 \mu A$	5 V	-	1.5	-	1.5	-	1.5	-	1.5	V
	input voltage		10 V	-	3.0	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	-	4.0	V
V _{OH}	HIGH-level	$ I_{O} < 1 \mu A$	5 V	4.95	-	4.95	-	4.95	-	4.95	-	V
	output		10 V	9.95	-	9.95	-	9.95	-	9.95	-	V
	voltage		15 V	14.95	-	14.95	-	14.95	-	14.95	-	V
V _{OL}	LOW-level	$ I_{O} < 1 \mu A$	5 V	-	0.05	-	0.05	-	0.05	-	0.05	V
	output voltage		10 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	-	0.05	V
I _{OH}	HIGH-level	V _O = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	-	-1.1	mΑ
	output current	V _O = 4.6 V	5 V	-	-0.64	-	-0.5	-	-0.36	-	-0.36	mΑ
		V _O = 9.5 V	10 V	-	-1.6	-	-1.3	-	-0.9	-	-0.9	mA
		V _O = 13.5 V	15 V	-	-4.2	-	-3.4	-	-2.4	-	-2.4	mA
I _{OL}	LOW-level	V _O = 0.4 V	5 V	0.64	-	0.5	-	0.36	-	0.36	-	mA
	output current	V _O = 0.5 V	10 V	1.6	-	1.3	-	0.9	-	0.9	-	mΑ
		V _O = 1.5 V	15 V	4.2	-	3.4	-	2.4	-	2.4	-	mΑ
I _I	input leakage current	V _{DD} = 15 V	15 V	-	±0.1	-	±0.1	-	±1.0	-	±1.0	μΑ
I _{DD}	supply	I _O = 0 A	5 V	-	5	-	5	-	150	-	150	μΑ
	current		10 V	-	10	-	10	-	300	-	300	μА
			15 V	-	20	-	20	-	600	-	600	μА
Cı	input capacitance		-	-	-	-	7.5	-	-	-	-	pF

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10. Dynamic characteristics

Table 7. Dynamic characteristics

 $V_{SS} = 0 \text{ V; } T_{amb} = 25 \text{ °C; for test circuit see }$ <u>Figure 7; unless otherwise specified.</u>

Symbol	Parameter	Conditions	V_{DD}	Extrapolation formula	Min	Тур	Max	Unit
t _{PHL}	HIGH to LOW	CP to Qn	5 V 🛚 🖸	98 ns + (0.55 ns/pF)C _L	-	125	250	ns
	propagation delay	see Figure 4	10 V	44 ns + (0.23 ns/pF)C _L	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	80	ns
		PL to Qn	5 V	93 ns + (0.55 ns/pF)C _L	-	120	240	ns
		see Figure 4	10 V	44 ns + (0.23 ns/pF)C _L	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	80	ns
t _{PLH}	LOW to HIGH propagation delay	CP to Qn	5 V 🖽	88 ns + (0.55 ns/pF)C _L	-	115	230	ns
		see Figure 4	10 V	39 ns + (0.23 ns/pF)C _L	-	50	100	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	80	ns
		PL to Qn	5 V	78 ns + (0.55 ns/pF)C _L	-	105	210	ns
		see Figure 4	10 V	39 ns + (0.23 ns/pF)C _L	-	50	100	ns
			15 V	32 ns + (0.16 ns/pF)CΛ	-	40	80	ns
transition time	Qn; see Figure 4	5 V [1	10 ns + (1.00 ns/pF)C _L	-	60	120	ns	
			10 V	9 ns + (0.42 ns/pF)C _L	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C _L	-	20	40	ns
t _{su} set-up time	set-up time	DS to CP;	5 V		+25	-15	-	ns
		see <u>Figure 5</u>	10 V		+25	-10	-	ns
			15 V		+15	-5	-	ns
		Dn to PL; see <u>Figure 6</u>	5 V		50	25	-	ns
			10 V		30	10	-	ns
			15 V		20	5	-	ns
t _h	hold time	DS to CP;	5 V		40	20	-	ns
		see Figure 5	10 V		20	10	-	ns
			15 V		15	8	-	ns
		Dn to PL;	5 V		+15	-10	-	ns
		see Figure 6	10 V		15	0	-	ns
			15 V		15	0	-	ns
t _W	pulse width	CP = LOW;	5 V		70	35	-	ns
		minimum width;	10 V		30	15	-	ns
		see <u>Figure 5</u>	15 V		24	12	-	ns
		PL = HIGH;	5 V		70	35	-	ns
		minimum width;	10 V		30	15	-	ns
		see <u>Figure 6</u>	15 V		24	12	-	ns
t _{rec}	recovery time	PL input;	5 V		50	10	-	ns
		see Figure 6	10 V		40	5	-	ns
			15 V		35	5	-	ns

 Table 7.
 Dynamic characteristics ...continued

 $V_{SS} = 0 \text{ V}$; $T_{amb} = 25 \text{ °C}$; for test circuit see <u>Figure 7</u>; unless otherwise specified.

Symbol	Parameter	Conditions	V_{DD}	Extrapolation formula	Min	Тур	Max	Unit
f _{clk(max)}		CP input;	5 V		6	13	-	MHz
	frequency	see Figure 5	10 V		15	30	-	MHz
			15 V		20	40	-	MHz

^[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

Table 8. Dynamic power dissipation P_D

 P_D can be calculated from the formulas shown. $V_{SS} = 0$ V; $t_r = t_f \le 20$ ns; $T_{amb} = 25$ °C.

Symbol	Parameter	V _{DD}	Typical formula for P _D (μW)	where:
P_D	dynamic power	5 V	$P_D = 900 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	f_i = input frequency in MHz,
	dissipation	10 V	$P_D = 4300 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	f_o = output frequency in MHz,
		15 V	$P_{D} = 12000 \times f_{i} + \Sigma (f_{o} \times C_{L}) \times V_{DD}^{2}$	C_L = output load capacitance in pF,
				V_{DD} = supply voltage in V,
				$\Sigma(f_0 \times C_L)$ = sum of the outputs.

11. Waveforms

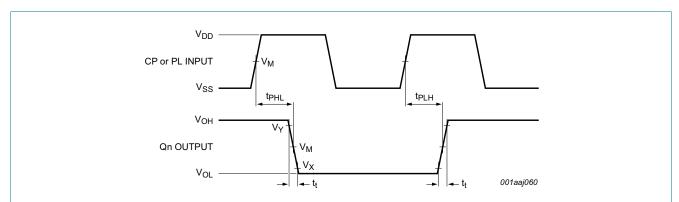


Fig 4. Waveforms showing propagation delays for CP and PL inputs to Qn output and Qn transition times

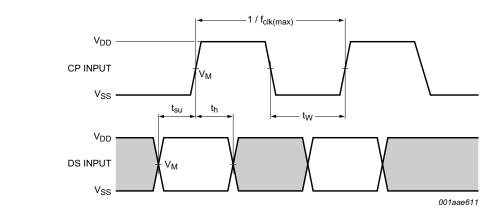


Fig 5. Waveforms showing minimum clock pulse width, set-up time, and hold time for CP and DS.

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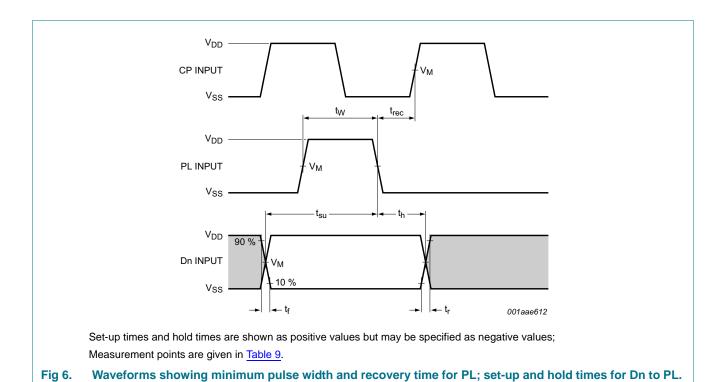
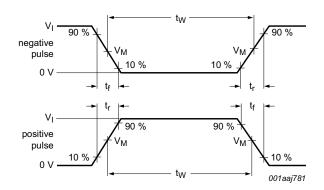
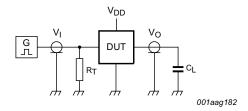


Table 9. Measurement points

Supply voltage	Input	Output				
V_{DD}	V _M	V _M	V_X	V _Y		
5 V to 15 V	0.5V _{DD}	0.5V _{DD}	0.1V _{DD}	0.9V _{DD}		



a. Input waveform



b. Test circuit

Test data is given in Table 10.

Definitions for test circuit:

DUT = Device Under Test.

 C_L = load capacitance including jig and probe capacitance.

 R_T = termination resistance should be equal to the output impedance Z_0 of the pulse generator.

Fig 7. Test circuit for measuring switching times

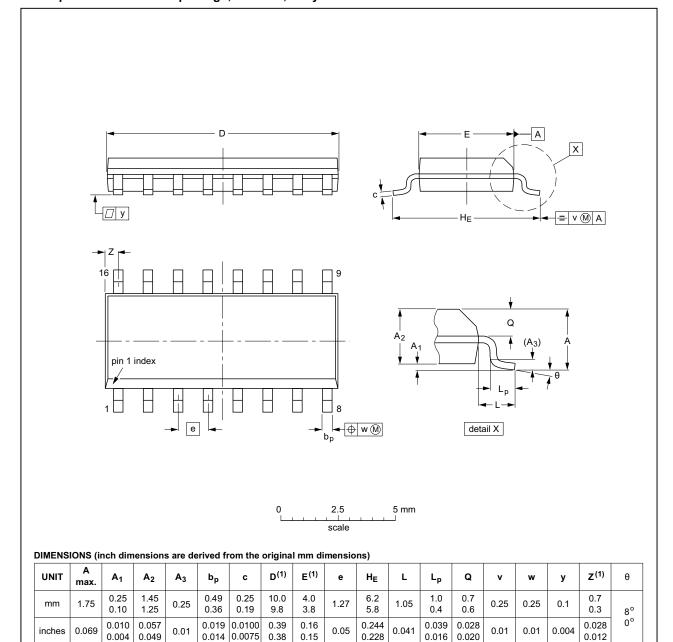
Table 10. Test data

Supply voltage	Input	Load	
V_{DD}	VI	t _r , t _f	CL
5 V to 15 V	V _{SS} or V _{DD}	≤ 20 ns	50 pF

12. Package outline

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1



Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

OUTLINE		REFER	RENCES	EUROPEAN ISSUE DATE		
VERSION	IEC	JEDEC JEITA		PROJECTION	ISSUE DATE	
SOT109-1	076E07	MS-012			99-12-27 03-02-19	

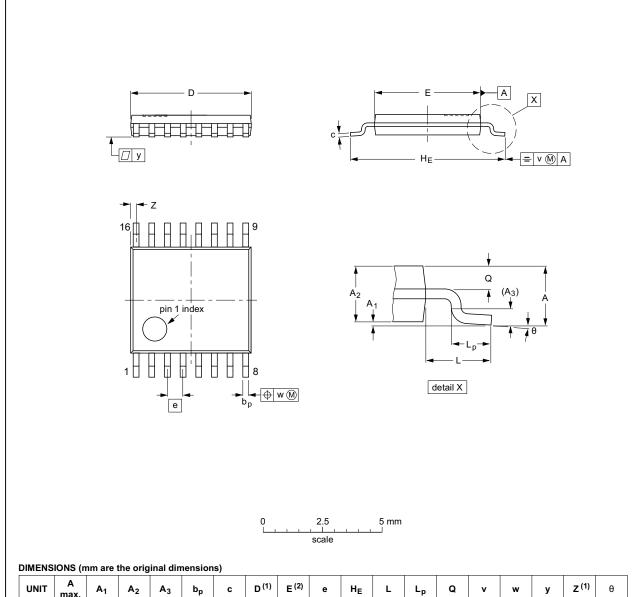
Fig 8. Package outline SOT109-1 (SO16)

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TSSOP16: plastic thin shrink small outline package; 16 leads; body width 4.4 mm

SOT403-1



UNI	Г A max	. A ₁	A ₂	A ₃	bp	C	D ⁽¹⁾	E (2)	е	HE	L	Lp	Q	v	w	у	Z ⁽¹⁾	θ
mm	1.1	0.15 0.05	0.95 0.80	0.25	0.30 0.19	0.2 0.1	5.1 4.9	4.5 4.3	0.65	6.6 6.2	1	0.75 0.50	0.4 0.3	0.2	0.13	0.1	0.40 0.06	8° 0°

Notes

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	EUROPEAN	ISSUE DATE		
VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE
SOT403-1		MO-153				-99-12-27 03-02-18
SOT403-1		MO-153				<u> </u>

Fig 9. Package outline SOT403-1 (TSSOP16)

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13. Revision history

Table 11. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes				
HEF4021B v.10	20160321	Product data sheet	-	HEF4021B v.9				
Modifications:	Type number	er HEF4021BP (SOT38-4) re	emoved.					
HEF4021B v.9	20130830	Product data sheet	-	HEF4021B v.8				
Modifications:	added type	number HEF4021BTT.	"					
HEF4021B v.8	20111118	Product data sheet	-	HEF4021B v.7				
Modifications:	Legal pages updated.							
	 Changes in "General description" and "Features and benefits". 							
	Section "Ap	plications" removed.						
HEF4021B v.7	20111010	Product data sheet	-	HEF4021B v.6				
HEF4021B v.6	20091127	Product data sheet	-	HEF4021B v.5				
HEF4021B v.5	20090707	Product data sheet	-	HEF4021B v.4				
HEF4021B v.4	20081110	Product data sheet	-	HEF4021B_CNV v.3				
HEF4021B_CNV v.3	19950101	Product specification	-	HEF4021B_CNV v.2				
HEF4021B_CNV v.2	19950101	Product specification	-	-				

14. Legal information

14.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions"
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Nexperia HEF4021B

8-bit static shift register

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